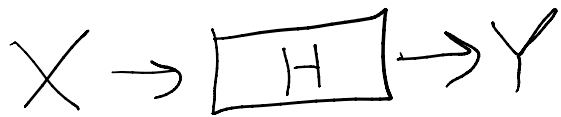


X WSS, H LTI \swarrow Even filter

then $S_x = \overline{\{R_x\}} \iff$ nonneg. real



then X, Y jointly WSS

$$S_y = |H|^2 S_x, \quad \mu_y = H(0) \mu_x$$

Def. X, Y jointly WSS, we define

$$S_{XY}(\omega) = \mathcal{F}\{R_{XY}\}$$

"Cross-spectral Density"

Gaussian Processes

Def random variables X_1, \dots, X_n are jointly Gaussian if every linear comb. of X_i 's is Gaussian

⊗ special case = X_1, \dots, X_n independent, identical Gaussian

Def a random process $X(t)$ is a Gaussian process if $\forall n \in \mathbb{N}, \forall (t_1, \dots, t_n) \in \mathbb{R}^n$
 $\{X(t_1), X(t_2), \dots, X(t_n)\}$ are jointly gaussian.

⊗ special case indep. gaussian at all $t \in \mathbb{R}$
 identical

Def Jointly Gaussian Processes $X(t), Y(t)$ j.g. if $\forall n, m \in \mathbb{N}$
 $\forall (t_1, \dots, t_n, \tau_1, \dots, \tau_m) \in \mathbb{R}^{n+m}, \{X(t_1), \dots, Y(\tau_m)\}$ j.g. as r.v.s

$\forall (t_1, \dots, t_n, \tau_1, \dots, \tau_m) \in \mathbb{R}^{n+m}$, $\{X(t_1), \dots, Y(\tau_m)\}$ j.g.
as r.v.s

1) If $X(t)$ Gaussian, H LTI



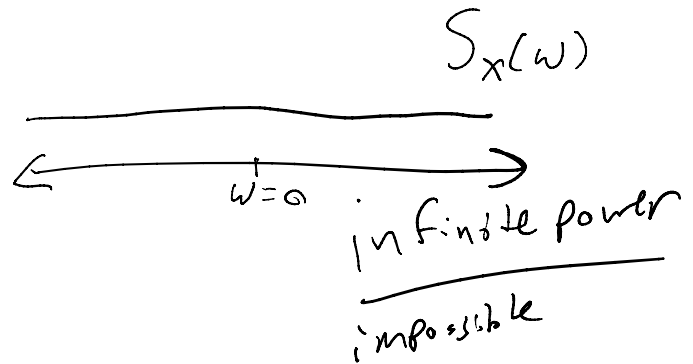
$X(t), Y(t)$ are jointly gaussian

2) For j.g. processes

Uncorrelated = independent

Def. A process is white if it has flat PSD

i.e. $S_x(\omega)$ is constant fcn



$$P_x = \infty$$

usually, when we say "white" in practice, we mean flat PSD over the band of interest

if $S_x(\omega) = C \forall \omega$, then

$$\mathcal{F}^{-1}\{C\} = R_x(\tau) = C \delta(\tau)$$

autocorr. of a white process is δ , i.e. no two time indices are correlated with each other

Ex. $X(t)$ gaussian process, uncorr = indep.

So indep. identical gaussian at each $t \Rightarrow$ white

↑ most noise in this class is modeled

↑ most noise in this class is modeled this way

A W G N
Additive White Gaussian Noise

Signal $m(t)$

model for AWGN is

$$r(t) = m(t) + n(t)$$

↑ r.p. white gaussian

usually means indep. identical gaussian $\forall t$

Independent $N(0, \sigma^2)$ at all time

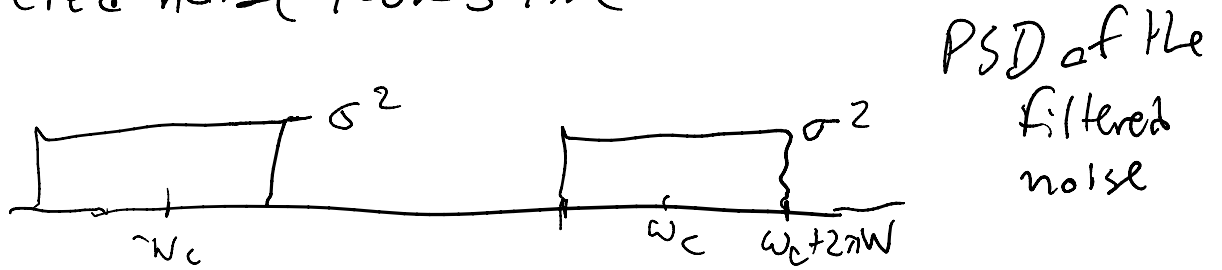
$$R(\tau) = 0 \quad \forall \tau \neq 0$$

$$R(0) = E[X^2] = \sigma^2$$

$$\mathcal{F}\{R(\tau)\} = \mathcal{F}\{\sigma^2 \delta(t-t_0)\} = \boxed{\sigma^2 = S_x(\omega)}$$

We will have a receiver which will filter all incoming signals to BW of interest

so filtered noise looks like

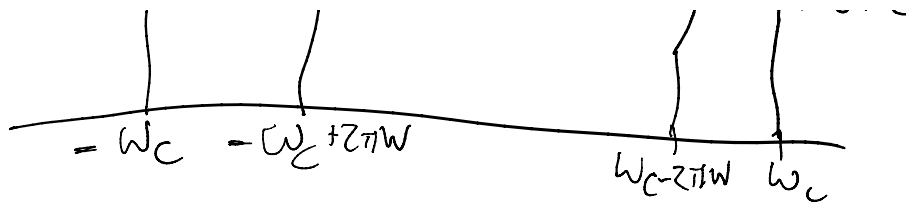


by convention, we say

$$\boxed{\sigma^2 = N_0/2}$$

← noise power





$$P_N = \frac{1}{2\pi} \int S_N(\omega) d\omega = \frac{N_0}{2} \frac{(2\pi W) 2}{2\pi} = N_0 W$$

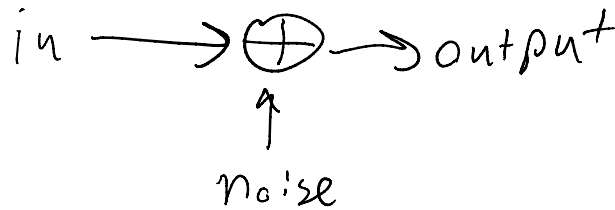
power in SSB noise is $N_0 W = 2\sigma^2 W$

power in DSB noise is $2N_0 W = 4\sigma^2 W$

Noise on Baseband Signals

Model noise as white $S_N(\omega) = N_0/2$

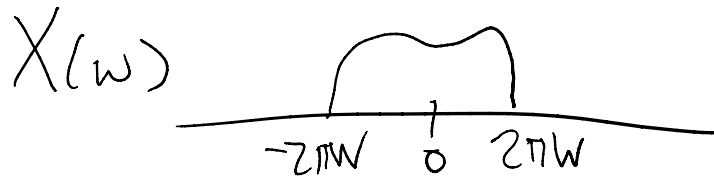
Channel model



AWN model



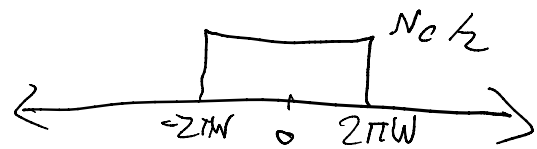
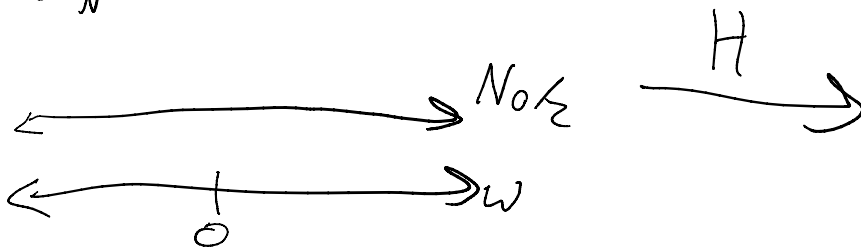
send bb signal



at the receiver, we apply BPF $H(\omega) = \begin{cases} 1, & |\omega| \leq 2\pi W \\ 0, & \text{else} \end{cases}$

$S_N(\omega)$

$$|H(\omega)|^2 S_N(\omega) = S_n(\omega)$$



$X(\omega) \xrightarrow{H} X(\omega)$ b/c $X(\omega) = 0$ for $|\omega| \geq 2\pi W$

$$X(\omega) \xrightarrow{\text{b/c}} \lambda(\omega) \quad \lambda(\omega) = \frac{N_0}{2} \quad (\omega \geq 2\pi W)$$

$P_N = \infty$ white noise has infinite power

$$P_n = \frac{1}{2\pi} \int_{-2\pi W}^{2\pi W} \frac{N_0}{2} d\omega = \frac{4\pi W}{2\pi} \frac{N_0}{2} = N_0 W \leftarrow \begin{array}{l} \text{power in} \\ \text{baseband} \\ \text{f. filtered noise} \end{array}$$

(if AWGN, $N_0 = 2\sigma^2$
so $P_n = 2\sigma^2 W$)

Obvious but important: additive $\rightarrow P_n$ is indep. of signal power

... Sort of...

P_n is a funcn of W , so $W \nearrow$ (is a prop. of the signal)
 $P_n \nearrow$

first example of the power-bw relationship (tradeoff)

Signal-to-Noise ratio (SNR) is the ratio

of received signal power over received noise power
(usually reported in dB)

in our case $SNR_{bb} = \frac{P_r}{N_0 W}$ \leftarrow power of received message signal

in our case

$$SNR_{bb} = \frac{P_r}{N_0 W}$$

⊗ $SNR_{dB} = 10 \log_{10} \left(\frac{P_r}{P_N} \right)$

10 b/c it's power

Ex. AWGN, variance 5×10^{-12}
 affects bb signal w/ bw 10 kHz

I transmit w/ 100 kW of power
 but the channel attenuates by a factor of 10^{-10}

$$P_R = (100 \text{ kW}) (10^{-10}) = 10^{-5} \text{ W}$$

$$P_N = N_b W = (10 \text{ kHz}) (\sigma^2 2) = (10^4 \text{ Hz}) (10^{-11})$$

$$= 10^{-7} \text{ W}$$

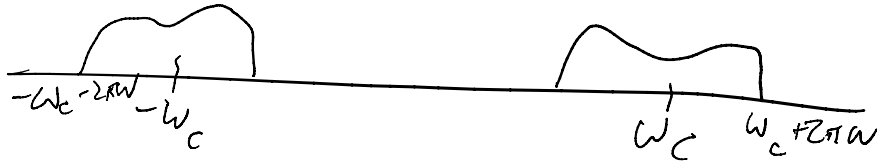
linear scale \rightarrow $SNR = \frac{P_R}{P_N} = \frac{10^{-5}}{10^{-7}} = 100$

log scale \rightarrow $SNR_{dB} = 10 \log_{10}(100) = 20 \text{ dB}$

DSB-SC

we transmit $u(t) = A_c m(t) \cos \omega_c t$

$|U(\omega)|$



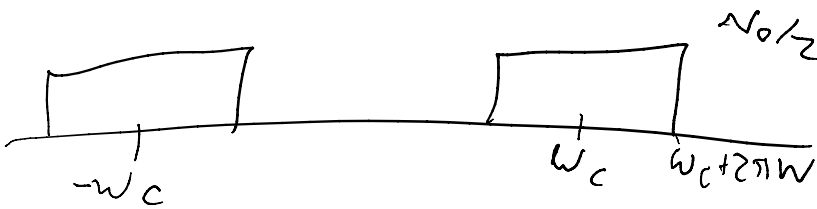
model: received = signal + AWW

$$r(t) = u(t) + n(t)$$

↪ filtered white noise
 $\omega_c - 2\pi W \leq |\omega| \leq \omega_c + 2\pi W$

Side track - talk about filtered white noise that isn't at bb

$S_N(\omega)$



just like w/ deterministic signals, we can write a bb rep. of this noise:

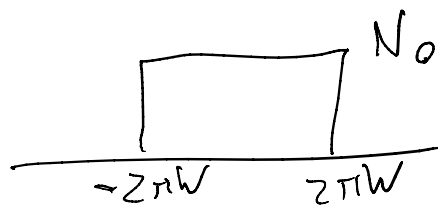
$$y(t) = \underbrace{I_n(t)}_{\text{random IQ processes}} \cos \omega_c t - \underbrace{Q_n(t)}_{\text{random IQ processes}} \sin \omega_c t$$

It can be shown that if X is white, Gaussian

1) I_n, Q_n are zero mean, baseband, jointly WSS and jointly gaussian

$$2) P_Y = P_{I_n} = P_{Q_n} \left(= \frac{1}{2\pi} \int S_Y(\omega) d\omega \right)$$

3) I_n and Q_n have same PSD



$$\text{So } P_{Q_n} = P_{I_n} = P_Y = 2N_0W$$

4) if ω_c is an axis of symmetry (i.e. in DSB) then I_n, Q_n are indep.

$$u(t) = A_c m(t) \cos \omega_c t$$



Can write $r(t) = u(t) + n(t)$

$$= u(t) + n_I(t) \cos \omega_c t - n_Q(t) \sin \omega_c t$$

Then we demodulate $r(t)$ by product w/ $\cos(\omega_c t + \varphi)$

then baseband filter

$$\cos a \cos b = \frac{1}{2} \cos(a+b) + \frac{1}{2} \cos(a-b)$$

$$\cos a \sin b = \frac{1}{2} (\sin(a+b) - \sin(a-b))$$

...

$$\cos a \sin b = \frac{1}{2}(\sin(a+b) - \sin(a-b))$$

$$r(t) \cos \omega_c t = A_c m(t) \cos \omega_c t \cos(\omega_c t + \varphi) + n_I(t) \cos \omega_c t \cos(\omega_c t + \varphi) - n_Q(t) \sin \omega_c t \cos(\omega_c t + \varphi)$$

↓ BBF: filter plus simplify

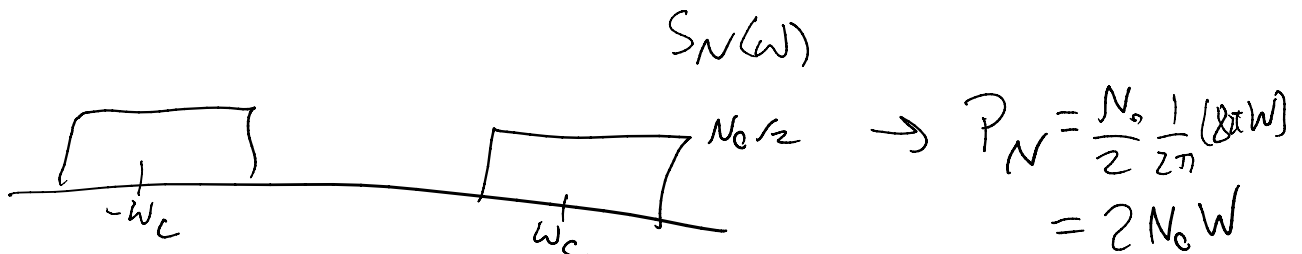
$$y(t) = \underbrace{\frac{1}{2} A_c m(t) \cos \varphi}_{\text{What we had w/ no noise}} + \underbrace{\frac{1}{2} (n_I(t) \cos \varphi + n_Q(t) \sin \varphi)}_{\text{+ bb noise}}$$

↑ this is stopping pt for non-coherent
assume coherent, then $\varphi = 0$

$$y(t) = \underbrace{\frac{1}{2} A_c m(t)}_{\substack{\text{what we had} \\ \text{w/ no noise} \\ \text{for coh.}}} + \underbrace{\frac{1}{2} n_I(t)}_{P_{n_I} = P_N \text{ by point (2)}}$$

So power in signal (as before) is $P_o = \frac{A_c^2}{4} P_M$

Power in noise is $\frac{1}{4} P_N = P_{n_o}$



So power in noise $P_{n_o} = \frac{N_o W}{4} = \sigma^2 W$

So power in noise $P_{n_0} = \frac{N_0 W}{2} = \sigma^2 W$

$$SNR_{\substack{\text{DSB-SC} \\ \text{Coherent}}} = \frac{A_c^2 / 4 P_M}{N_0 W / 2} = \boxed{\frac{A_c^2}{2 N_0 W} P_M}$$

$$= \frac{A_c^2}{4 \sigma^2 W} P_M$$

SNR_{bb} was $\frac{P_R}{N_0 W}$, $P_R = \frac{1}{T} \int_0^T (A_c \cos \omega_c t m(t))^2 dt$

$$= \frac{A_c^2 P_M}{2}$$

$$SNR_{bb} = \frac{P_R}{N_0 W} = \frac{A_c^2 P_M}{2 N_0 W} = SNR_{\text{DSB-SC}}$$

coherent DSB-SC has same SNR as BB

SSB

$r(t) = u(t) + n(t)$ AWGN _{DSB}

$u(t) = A_c m(t) \cos \omega_c t \mp A_c \hat{m}(t) \sin \omega_c t$

\swarrow $\hat{m}(t)$ \nearrow
 LSSB

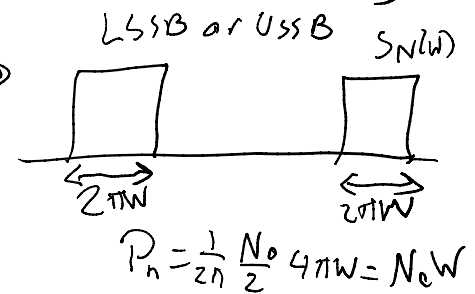
$$r(t) = (A_c m(t) + n_I(t)) \cos \omega_c t - (\mp A_c \hat{m}(t) + n_Q(t)) \sin \omega_c t$$

↓ demod + BB filter, assume coherent

$$y(t) = \frac{A_c}{2} m(t) + \frac{1}{2} n_z(t) \quad (\text{for USSB or LSSB})$$

$$= P_o + P_{nc} = \frac{A_c^2}{4} P_m + \frac{1}{4} P_n \rightarrow$$

$$SNR_{SSB} = \frac{\frac{1}{4} A_c^2 P_m}{\frac{1}{4} N_o W} = \boxed{\frac{A_c^2 P_m}{N_o W}}$$



Seems better than DSB

but we transmitted $m(t)$ and $\hat{m}(t)$ at same power
So we receive 2 times signal power

so if $P_R^{DSB} = \frac{A_c^2}{2} P_m$, then $P_R^{SSB} = A_c^2 P_m$

$$\boxed{SNR_{SSB} = \frac{P_R}{N_o W} = SNR_{ob} = SNR_{DSB-xc}}$$

P_R is more directly related to transmitted power ← True Cost

Whereas P_{signal} in SNR computation is demod signal power

SSB - transmit 2x power, half BW, same SNR

Power/BW tradeoff

Conventional

Tuesday, September 22, 2020 7:43 PM

$$u(t) = A_c(1 + a m(t)) \cos \omega_c t$$

$$r(t) = (A_c(1 + a m(t)) + n_c(t)) \cos \omega_c t - n_s(t) \sin \omega_c t$$

before if I $\otimes \cos \omega_c t$,

I get rid of $n_s(t)$ by $\cos \uparrow \sin$

here, demod is rectifier + LPF \rightarrow doesn't
get rid of n_c

Using Conventional demod \rightarrow quadrature component noise
 \rightarrow Worse than DSB or SSB

What if I have conventional AM on a demod line regular?
= Like DSB AM, with a pilot tone

\downarrow

$$y_1(t) = \underbrace{\frac{1}{2} A_c(1 + a m(t))}_{DC} + \frac{1}{2} n_I(t)$$

\downarrow use a DC-block (Capacitor)

$$y(t) = \frac{a A_c}{2} m(t) + \frac{1}{2} n_I(t)$$

$$P_N = P_N^{DSB} = \frac{2 N_c W}{4}$$

$$P_R = \frac{A_c^2}{2} (a^2 P_m + 1)$$

$$P_o = \frac{a^2 A_c^2 P_m}{4}$$

$$P_0 = \frac{a^2 A_c^2 P_m}{4}$$

$$\text{So } \text{SNR}_{\text{DSB-com}} = \frac{a^2 A_c^2 P_m}{2 N_c W} = \frac{a^2 P_m}{1 + a^2 P_m} \frac{\frac{A_c^2}{2} (a^2 P_m + 1)}{N_0 W}$$

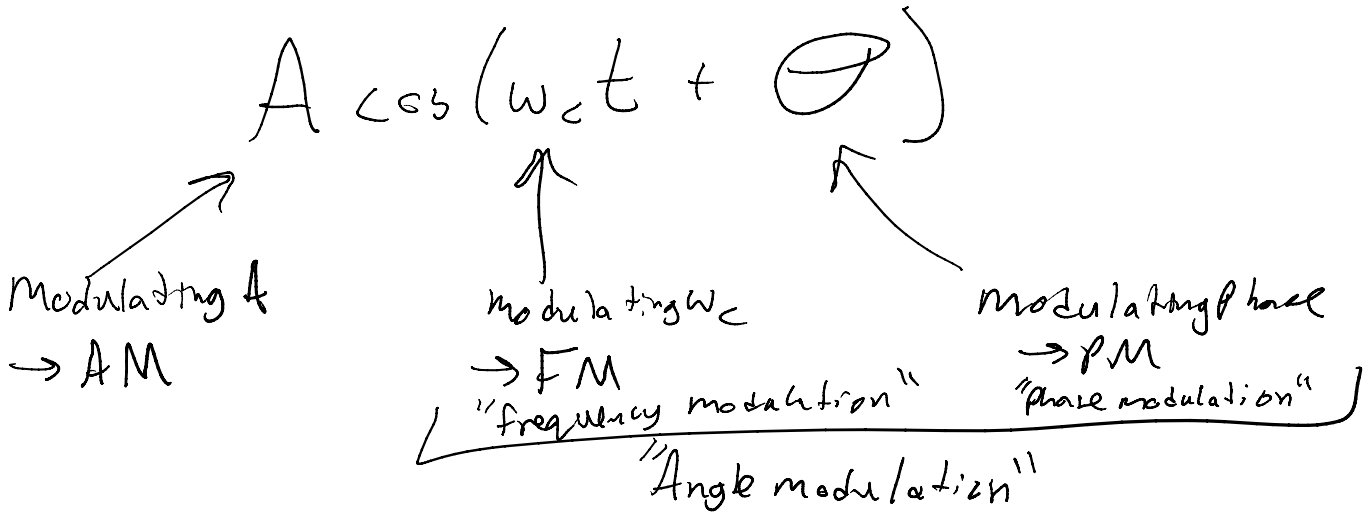
$$\eta = \frac{a^2 P_m}{1 + a^2 P_m} < 1 \quad = \eta \frac{P_R}{N_0 W} = \eta \text{SNR}_{\text{bb}}$$

So with a pilot tone, SNR decreased by η
waste power in pilot tone

Useless carrier component \rightarrow large part of P_R

FM/PM

Tuesday, September 22, 2020 7:55 PM



Big Problem - not intuitive at all
- Nonlinear - modulating the argument of a transcendental function

we have to rely on math more than intuition
hard

Generally: write any angle-modulated signal as
$$u(t) = A_c \cos(\omega_c t + \phi(t))$$

how will this affect frequency content of the signal?

one simple example let $\phi(t) = \omega_0 t + \theta$ - general linear phase

$$u(t) = A_c \cos((\omega_c + \omega_0)t + \theta)$$

increased freq

but still narrowband

w.l. + if $\phi(t) = \sin \omega_0 t$? - we have no tools to ..

what if $\varphi(t) = \sin \omega_0 t$? — We have no tools to deal with this yet

Def. The instantaneous frequency of an angle-modulated signal $u(t) = A_c \cos(\omega_c t + \varphi(t))$ is

$$f_i(t) = f_c + \frac{1}{2\pi} \frac{d}{dt} \varphi(t)$$

or

$$\omega_i(t) = \omega_c + \frac{d}{dt} \varphi(t) \text{ in radian freq.}$$

in above example, $\varphi(t) = \omega_0 t + \theta$, $\varphi'(t) = \omega_0$

$$\omega_i = \omega_c + \omega_0 = \text{freq. of mod. signal}$$

"more-or-less" freq. of signal at time t

in FM

Tuesday, September 22, 2020 8:10 PM

We let $\varphi(t) = k_p m(t)$ → phase \propto message

in FM

We let the instantaneous freq. deviation is prop.

to the message $f_i - f_c \propto m$

$$f_i(t) - f_c = k_f m(t) = \frac{1}{2\pi} \frac{d}{dt} \varphi(t)$$

in FM $\varphi \propto \int m(t) dt$

Specifically

$$\varphi(t) = 2\pi k_f \int_{-\infty}^t m(\tau) d\tau$$

FM might better be called "instantaneous freq. mod"

How do we demod?
 we want to find $\phi(t)$ somehow

ex. Let $m(t) = a \cos \omega_0 t$

PM: $\phi(t) = a k_p \cos \omega_0 t$

FM: $\phi(t) = 2\pi a k_f \int_{-\infty}^t \cos \omega_0 \tau d\tau$

$$= \frac{2\pi a k_f}{\omega_0} \sin \omega_0 t$$

$$u_{PM}(t) = A_c \cos(\omega_c t + a k_p \cos \omega_0 t)$$

$$u_{FM}(t) = A_c \cos(\omega_c t + \frac{2\pi a k_f}{\omega_0} \sin \omega_0 t)$$

def $\tilde{\beta}_p = a k_p, \tilde{\beta}_f = \frac{a k_f}{f_0}$

$$u_{PM}(t) = A_c \cos(\omega_c t + \tilde{\beta}_p \cos \omega_0 t)$$

$$u_{FM}(t) = A_c \cos(\omega_c t + \tilde{\beta}_f \sin \omega_0 t)$$

PM: Phase changes by at most $\tilde{\beta}_p$
 More generally: $k_p \max(|m(t)|) = \Delta \phi_{max}$

$\Gamma_{PM} = \frac{1}{2\pi} \int_{-\infty}^{\infty} \max(|m(t)|) dt$

$$FM: \frac{k_f \max(|m(t)|)}{W} = \Delta f_{\max}, W \text{ BW of } M(\omega)$$

Def modulation index

$$PM: \beta_p = k_p \max(|m(t)|) = \Delta \phi_{\max}$$

$$FM: \beta_f = \frac{k_f \max(|m(t)|)}{W} = \frac{\Delta f_{\max}}{W}$$

Special case $\phi(t) \ll 1 \forall t$ (low mod. index)
 "low index" or "Narrowband" FM/PM

$$u(t) = A_c \cos(\omega_c t + \phi(t))$$

$$= A_c \cos(\omega_c t) \cos(\phi(t)) - A_c \sin(\omega_c t) \sin(\phi(t))$$

$$\approx A_c \cos \omega_c t - A_c \phi(t) \sin \omega_c t$$

$$\uparrow$$

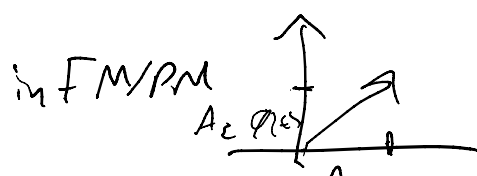
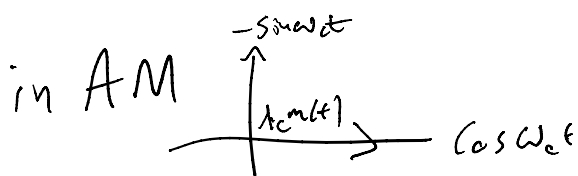
$$\cos x \approx 1$$

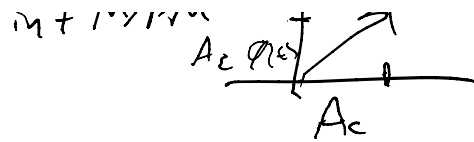
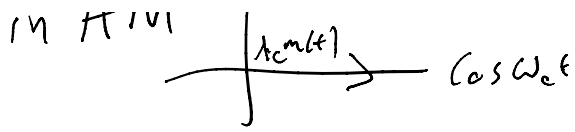
$$\uparrow$$

$$\sin x \approx x$$

for small x

$$I(t) = A_c, \quad Q(t) = A_c \phi(t)$$

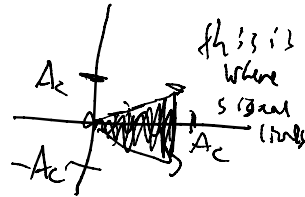




narrowband $\rightarrow I(t) = A_c \cos(\omega_c t)$ $Q(t) = A_c \phi(t)$

more generally $\rightarrow I(t) = A_c \cos(\phi(t))$, $Q(t) = A_c \sin(\phi(t))$

\leftarrow range $[-A_c, A_c]$ \rightarrow



In the freq. domain

Special case $m(t) = a \cos \omega_0 t$

$$u_{FM}(t) = A_c \cos(\omega_c t + \beta_f \sin \omega_0 t)$$

$$= \text{Re} (A_c e^{j\omega_c t} e^{j\beta_f \sin \omega_0 t})$$

\approx periodic with period $T = \frac{2\pi}{\omega_0}$

So we can rep. as a Fourier Series

$$e^{j\beta_f \sin \omega_0 t} = \sum_{n=-\infty}^{\infty} c_n e^{jn\omega_0 t}$$

where

$$c_n = \frac{1}{T} \int_0^T e^{j\beta_f \sin \omega_0 t} e^{-jn\omega_0 t} dt$$

$$1, n \neq 0; (\beta_f \sin u - nu)$$

def. of F.S.

$$= \frac{1}{2\pi} \int_0^{2\pi} e^{j(\beta \sin u - nu)} du, \quad u = \omega t$$

Evaluate this integral X it's impossible

This is an indexed set of functions of β with a name!

Def. The n^{th} order Bessel Function of the first kind for integer n $J_n: \mathbb{R} \rightarrow \mathbb{R}$ is def as

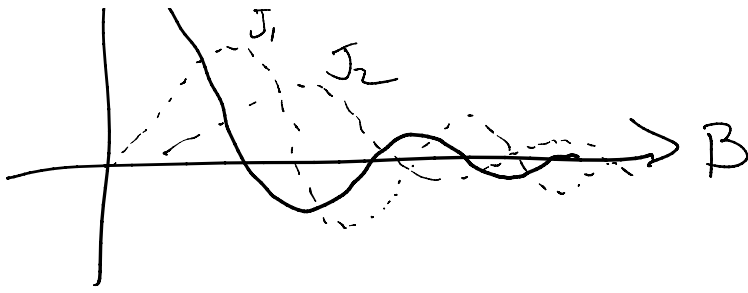
$$J_n(\beta) = \frac{1}{2\pi} \int_0^{2\pi} e^{j(\beta \sin u - nu)} du$$

Shockingly useful

We have a lot of info about Bessel Fncs

- 1) $J_{-n} = (-1)^n J_n$, so $|J_n(\beta)| = |J_{-n}(\beta)|$
- 2) $\max_{\beta > 0} (J_n(\beta)) > \max_{\beta > 0} (J_{n+1}(\beta)) \forall n$
- 3) I will draw them for you poorly





$$4) J_n(B) = \sum_{k=0}^{\infty} \frac{(-1)^k (\beta/2)^{n+2k}}{k! (n+k)!}$$

for small β , $J_n(\beta) \approx \frac{\beta^n}{2^n n!}$

so as $n \uparrow$
 $J_n(\beta) \downarrow$ for small β

For higher β , you need more modes to estimate power

for $\beta \leq 8$ can get 98% power est. with < 10
terms of sum

$$u(t) = \text{Re} \left(A_c \sum_{n=-\infty}^{\infty} J_n(\beta) e^{j\omega_c t} e^{j n \omega_m t} \right)$$

$$= A_c \sum_{n=-\infty}^{\infty} J_n(\beta) \cos((\omega_c + n\omega_m)t)$$

whoa...

I transmit one tone and my FM signal has
infinite BW

freq. of signal was mod. \rightarrow nonlinear op

but $J_n \downarrow$ as $n \rightarrow \infty$, it decays in freq.

So angle mod. signals are infinite BW

but approximately finite BW

So we can lose a little info in high freq. components
and filter before TX and after RX

$$4X'(t) + X(t - T)$$

$$X(t) \rightarrow [H_1] \rightarrow X(t - T)$$

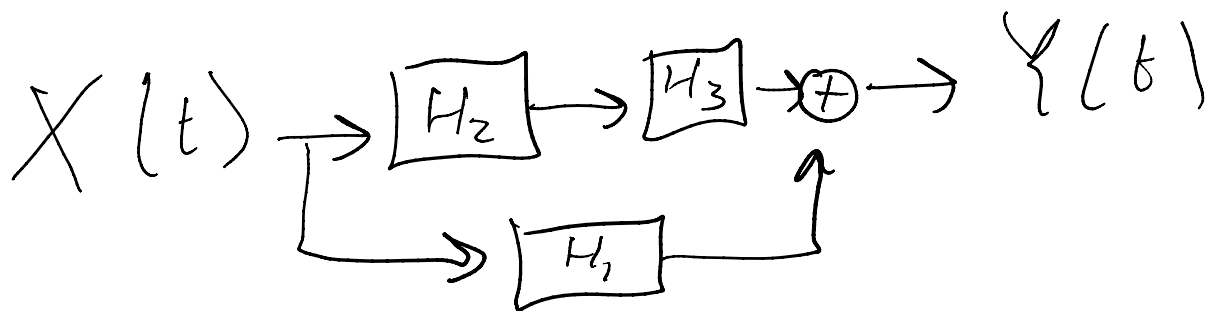
$$H_1 = e^{j\omega T}$$

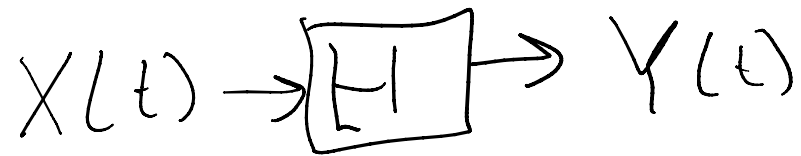
$$X(t) \rightarrow [H_2] \rightarrow 4X(t)$$

$$H_2 = 4$$

$$X(t) \rightarrow [H_3] \rightarrow X'(t)$$

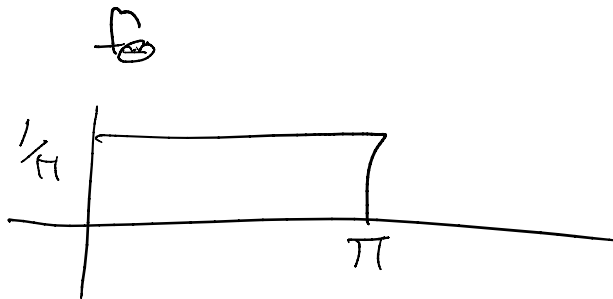
$$H_3 = j\omega$$





$$H = H_2 H_3 + H_1$$

$$= 4j\omega + e^{j\omega T}$$



$$P(\sin\theta \geq 1/2 \text{ and } \cos\theta \geq 1/2)$$

$$P(\sin\theta > 1/2) P(\cos\theta > 1/2)$$

$$R_x = E[\sim]$$

sample autocorr = sample mean(\sim)

↓ as $N \nearrow$

$$E[\sim]$$